

# Machine Learning



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2023

# Anomaly Detection

A decorative horizontal bar at the bottom of the slide, consisting of a red segment on the left and a teal segment on the right.

# Anomaly Detection [Outlier Data Detection]

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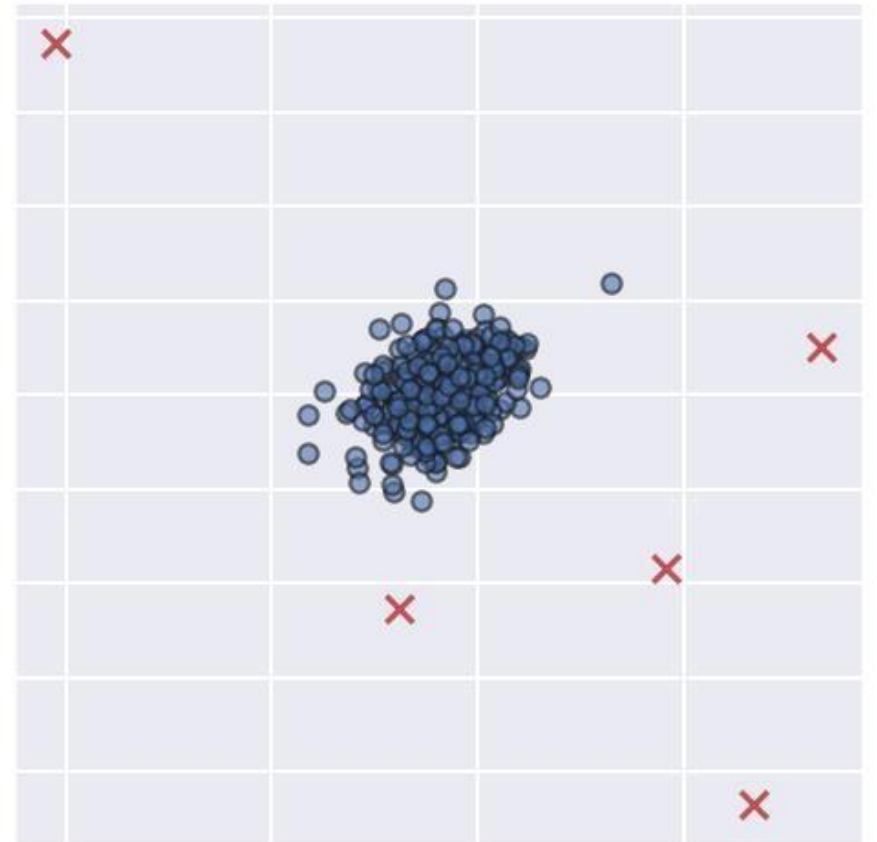
❑ **Anomaly Detection.** Identifying observations that differ greatly from most observations.

❑ **Scam Detection.**

- Detection of highly improbable transactions by the credit cardholder.

❑ **Network Security.**

- Detecting activities with very low probability by legal user is done.

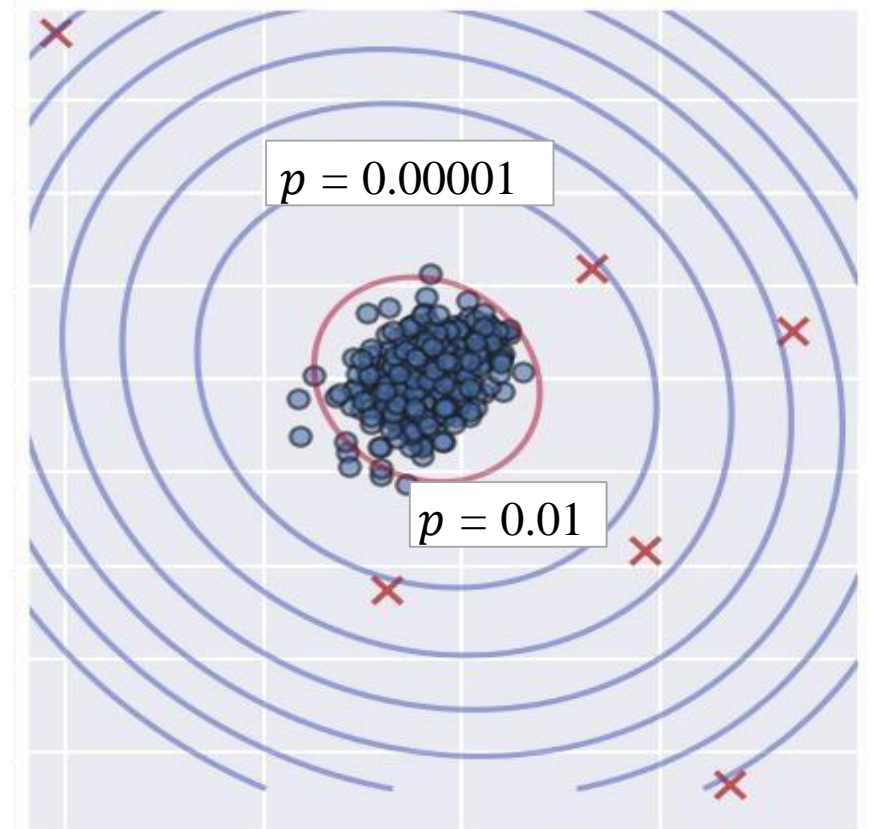


# Anomaly Detection [Outlier Data Detection]

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- ❑ **Anomaly Detection.** Identifying observations that differ greatly from most observations.
- ❑ **A probabilistic approach to anomaly detection.**
  - ❑ Creating a probabilistic model from the data  
[Expressing the probability of seeing any possible event]
  - ❑ Specify observations that are very unlikely to occur.

$$p(x) < \epsilon$$





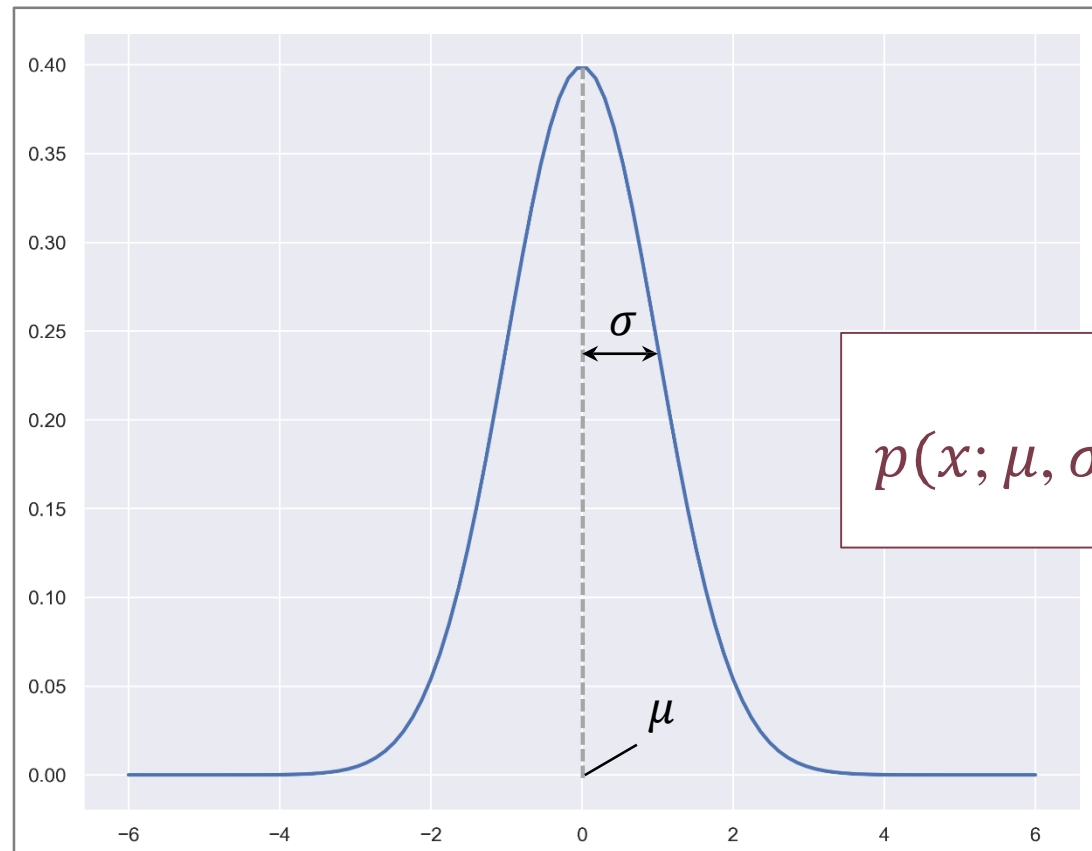
# Gaussian Distribution(Normal)

# Gaussian Distribution

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- **Gaussian Distribution.** Suppose  $x$  has Gaussian Distribution with average of  $\mu$  and variance is  $\sigma^2$ .

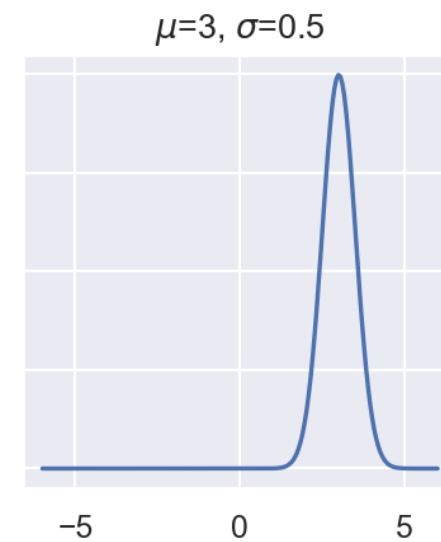
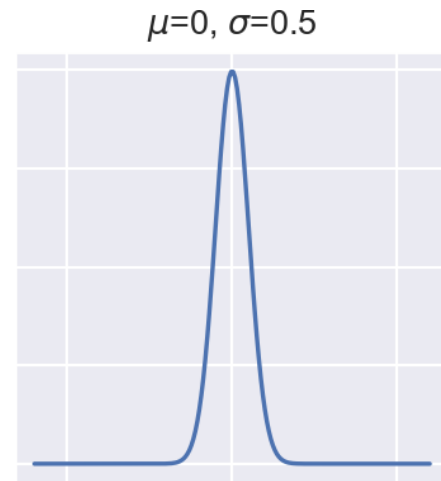
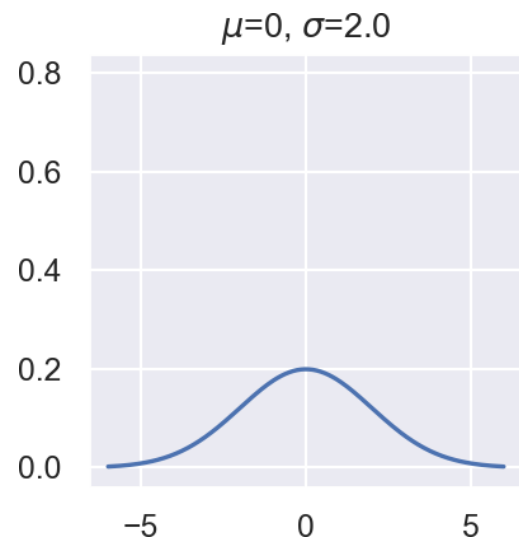
$$x \sim N(\mu, \sigma^2)$$



$$p(x; \mu, \sigma^2) = \frac{1}{\sigma\sqrt{2\pi}} e^{\left(-\frac{(x-\mu)^2}{2\sigma^2}\right)}$$

# Univariate Gaussian Distribution

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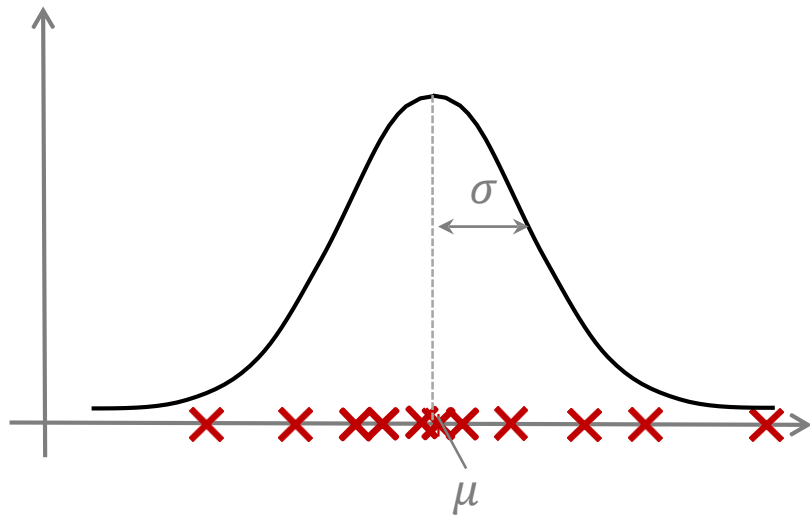


# Parameter Estimation

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- Data collection.
- Purpose. Estimation of values  $\mu$  and  $\sigma$

$$\{x^{(1)}, x^{(2)}, x^{(3)}, \dots, x^{(m)}\}$$



$$\mu = \frac{1}{m} \sum_{i=1}^m x^{(i)}$$

$$\sigma^2 = \frac{1}{m} \sum_{i=1}^m (x^{(i)} - \mu)^2$$



# Anomaly Detection Algorithm



# Estimation of Distribution

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□ Training set.

$$\{x^{(1)}, x^{(2)}, x^{(3)}, \dots, x^{(m)}\}, \quad x^{(i)} \in \mathbb{R}^n$$

□ Assumptions.

$$x_j \sim N(\mu_j, \sigma_j^2)$$

□ Features follow a normal distribution.

□ There is no correlation between features. [Diagonal covariance matrix]

$$\begin{aligned} p(\mathbf{x}) &= p(x_1; \mu_1, \sigma_1^2) p(x_2; \mu_2, \sigma_2^2) p(x_3; \mu_3, \sigma_3^2) \cdots p(x_n; \mu_n, \sigma_n^2) \\ &= \prod_{j=1}^n p(x_j; \mu_j, \sigma_j^2) \end{aligned}$$

# Anomaly Detection Algorithm

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- ❑ Determining features that can be useful in anomaly detection.
- ❑ Estimation of parameters (for  $n \geq j \geq 1$ )

$$\mu_j = \frac{1}{m} \sum_{i=1}^m x_j^i \quad \sigma_j^2 = \frac{1}{m} \sum_{i=1}^m (x_j^i - \mu_j)^2$$

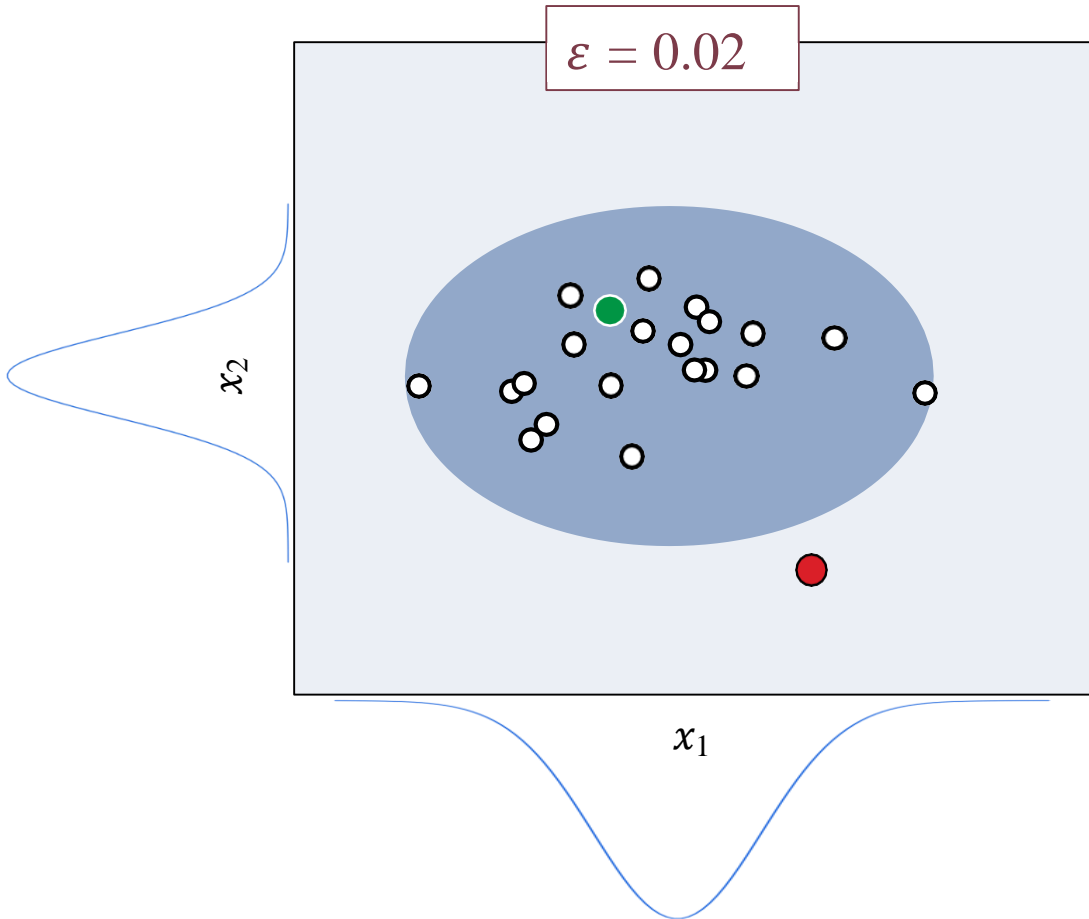
- ❑ Calculation  $p(x)$  for the new data of  $x$

$$P(x) = \prod_{j=1}^n p(x_j; \mu_j; \sigma_j^2) = \prod_{j=1}^n \frac{1}{\sigma_j \sqrt{2\pi}} \exp\left(-\frac{(x_j - \mu_j)^2}{2\sigma_j^2}\right)$$

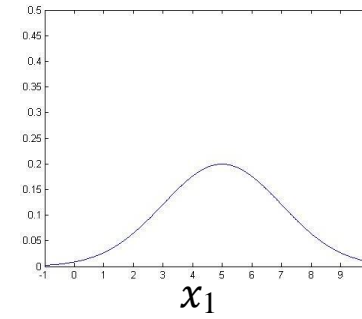
- ❑ Printing the <<yes>> output if  $p(x) < \epsilon$

# Example

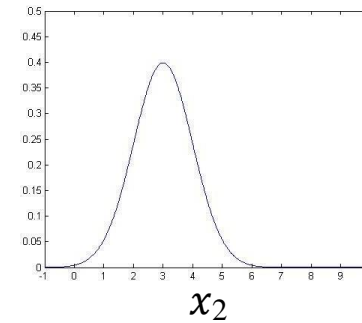
11



$$\mu_1 = 5, \sigma_1 = 2$$



$$\mu_2 = 3, \sigma_2 = 1$$



$$p(x_{test}^{(1)}) = 0.0426$$

$$p(x_{test}^{(2)}) = 0.0021$$

# Development and Measurement of Anomaly Detection Systems



# Numerical Evaluation

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## □ Importance.

□ During the process of developing learning systems, if we have a method to evaluate the system, then many decisions (such as feature selection, etc.) will become much simpler.

□ Suppose we have some labeled data that  $(y = 0)$  is its normality and its abnormality is  $(y = 1)$ .

## □ Training collection

$$\{x^{(1)}, x^{(2)}, x^{(3)} \dots, x^{(m)}\}$$

## □ Validation set.

$$\left\{ \left( x_{cv}^{(1)}, y_{cv}^{(1)} \right), \left( x_{cv}^{(2)}, y_{cv}^{(2)} \right), \dots, \left( x_{cv}^{(m_{cv})}, y_{cv}^{(m_{cv})} \right) \right\}$$

## □ Test set.

$$\left\{ \left( x_{test}^{(1)}, y_{test}^{(1)} \right), \left( x_{test}^{(2)}, y_{test}^{(2)} \right), \dots, \left( x_{test}^{(m_{test})}, y_{test}^{(m_{test})} \right) \right\}$$

# Example

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## ❑ Data collection. Engine performance information

- ❑ 10000 Unbroken engine
- ❑ 20 broken engine

## ❑ Data assortment.

- ❑ Training set.                   6000 unbroken engine [Single Category Assortment]
- ❑ Validation set.                2000 unbroken engine and 10 broken engine
- ❑ Experimental set.            2000 unbroken engine and 10 broken engine

# Algorithm Evaluation

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- ❑ **Instruction.** Development of the  $p(x)$  model according to the training set
- ❑ **Forecasting.** For samples in the validation or training set

$$y = \begin{cases} 1, & p(x) < \varepsilon \\ 0, & p(x) \geq \varepsilon \end{cases}$$

- ❑ **Possible evaluation factor.**
  - ❑ true positive, false positive, true negative, false negative
  - ❑ Accuracy rate and reminder rate
  - ❑ F1 score

- ❑ **Attention.** Validation set can be used to choose a suitable value for  $\varepsilon$ .



# Evaluation Factor

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- Evaluation factor. For unbalanced data

		real	
		$y = 1$	$y = 0$
predict	$y = 1$	TP	FP
	$y = 0$	FN	TN

$$Precision = \frac{TP}{TP + FP}$$

$$Recall = \frac{TP}{TP + FN}$$

$$F1 = 2 \frac{P \cdot R}{P + R}$$

Anomaly Detection or Supervised Learning?



# Anomaly detection or supervised learning?

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## Monitored Learning

- ❑ Number of samples.
  - ❑ Large numbers of positive and negative samples
- ❑ Positive sample.
  - ❑ Number of positive examples for the algorithm to understand them, is enough.
- ❑ New positive samples are similar to positive ones that the algorithm was previously faced, during the training process.

## Anomaly Detection

- ❑ Number of samples.
  - ❑ The ratio of the number of positive to negative samples is very low
- ❑ Different “Types” of anomalies.
  - ❑ For any algorithm, learning anomalies from small numbers of positive samples is very difficult.
  - ❑ New anomalies may not be similar to anomalies that have been seen before.

# Anomaly detection or monitored learning?

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## Monitored learning

- Spam detection.
- Weather forecast.
- Diagnosis of malignant cancerous tumors.
- ...

## Anomaly detection

- Scam detection
- Construction and production (making airplane engines).
- Monitoring machines in data centers.
- ...

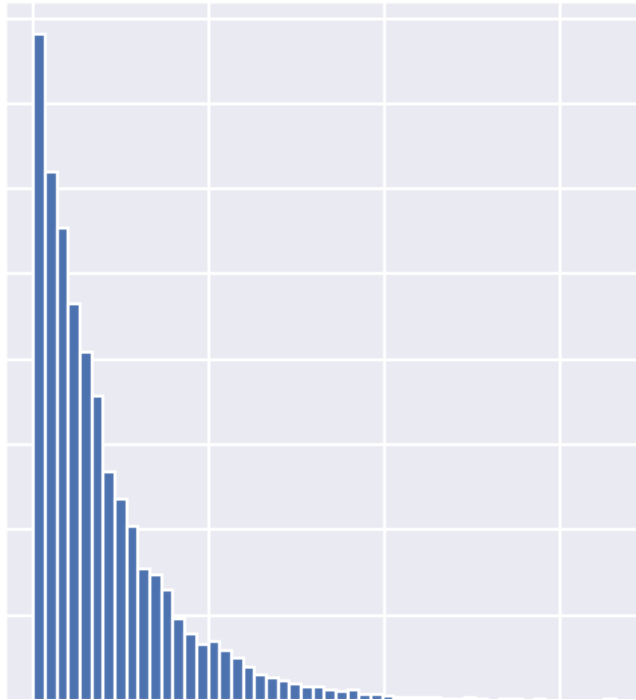
Select Features



# Converting the Feature with Abnormal Distribution to the Feature with Normal Distribution

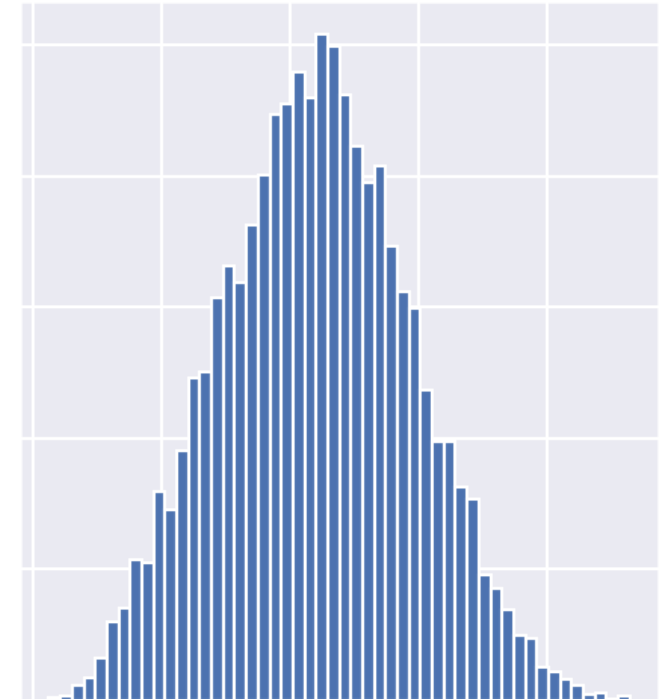
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Original Data (Gamma Distribution)



$x^{0.3}$

Transformed Data (Normal Distribution)



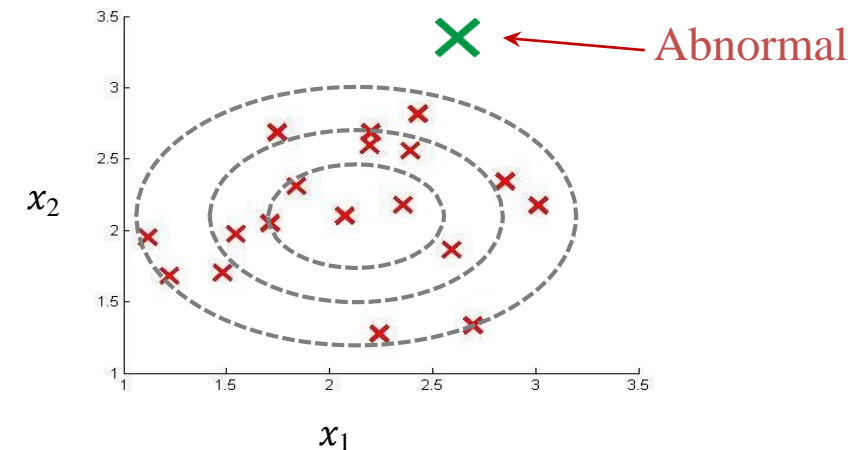
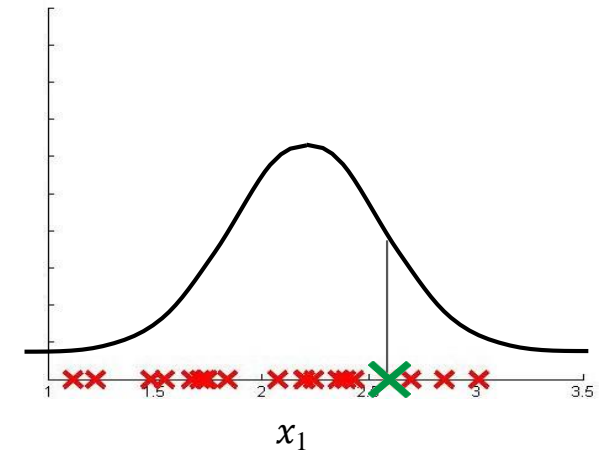
```
x = np.random.gamma(1, 2, (10000, 1))  
plt.hist(x, 50)
```

```
plt.hist(x ** 0.3, 50)
```

# Error Analysis for Helping in Anomaly Detection

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- ❑ Purpose. We want  $p(x)$  value:
  - ❑ Be large for normal data.
  - ❑ Be small for abnormal data.
  
- ❑ A common problem.
  - ❑ There is no differences between normal and abnormal for  $p(x)$ .



# Monitor Computers in Data Centers

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- ❑ Features selecting. Selection of features that are **very small** or **very large** if there is an anomaly.
  - ❑ Memory usage
  - ❑ Number of disk accesses per second
  - ❑ Processor load
  - ❑ Network traffic
  
- ❑ Add new features to detect abnormal conditions.
  - ❑ The ratio of processor load to network traffic
    - [For example, if the processor is stuck in an infinite loop, the value of this feature will be very large.]

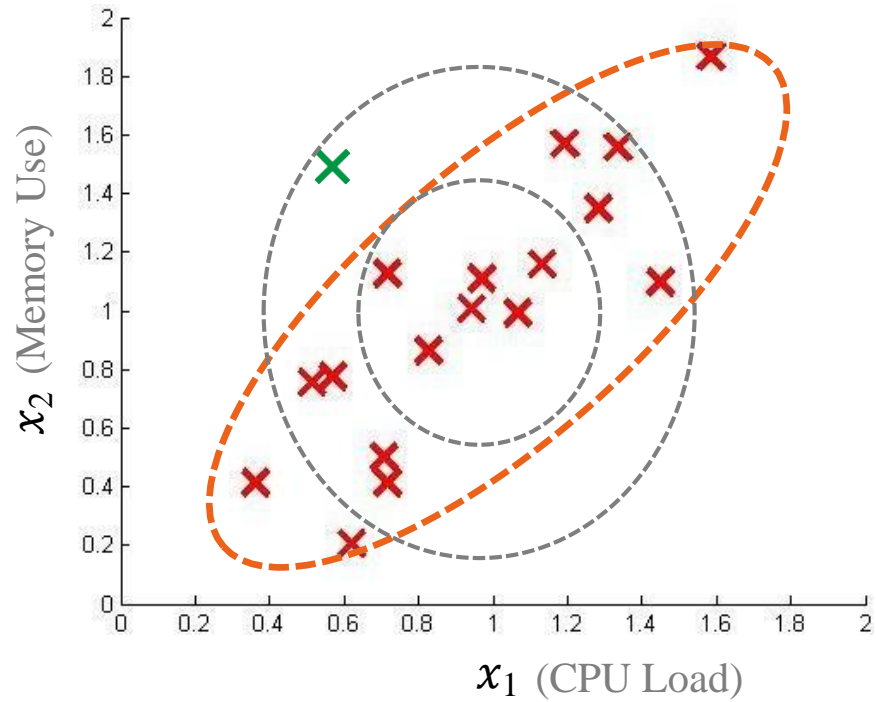


# Multivariate Gaussian Distribution

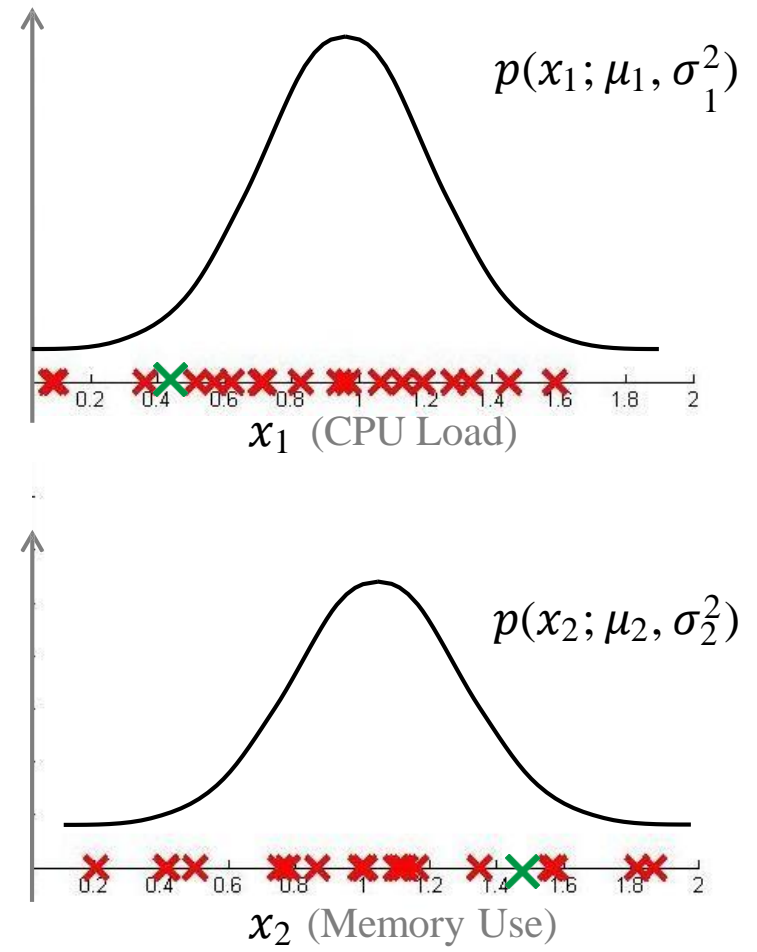


# Introductory Example

Bivariate Gaussian function



As the processor load increases, memory consumption normally increases.



# Bivariate Gaussian function

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## □ Bivariate Gaussian function.

$$p(\mathbf{x}; \mu, \Sigma) = \frac{1}{|\Sigma|^{1/2} (2\pi)^{n/2}} \exp\left(-\frac{1}{2} (\mathbf{x} - \mu)^T \Sigma^{-1} (\mathbf{x} - \mu)\right)$$

## □ Parameters

$$\mu \in \mathbb{R}^n$$

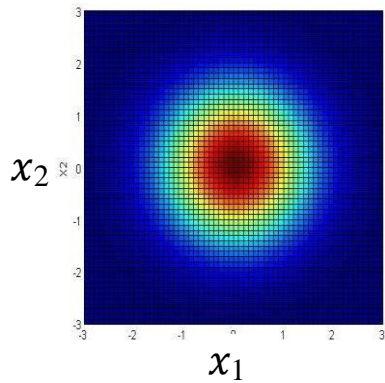
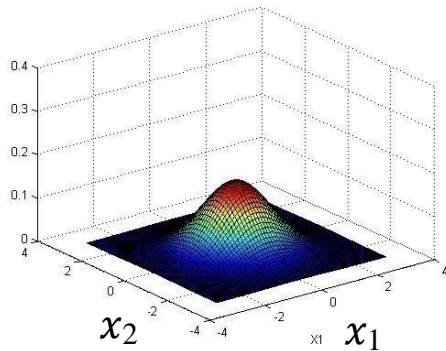
Covariance Matrix


$$\Sigma \in \mathbb{R}^{n \times n}$$

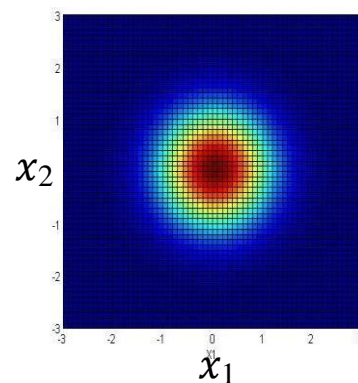
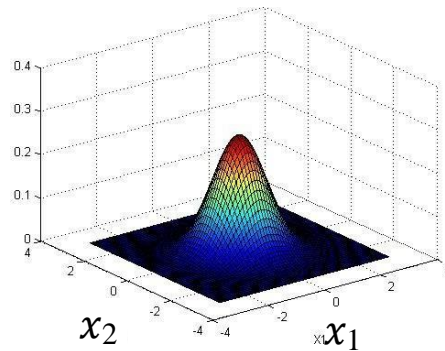
# Diagonal Covariance Matrix, the Variance of Features is Equal

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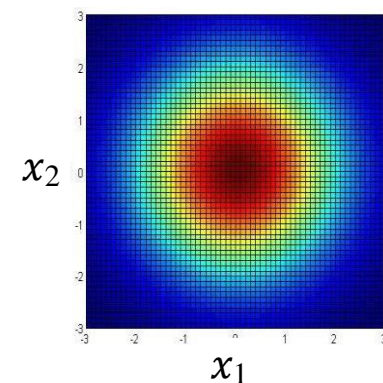
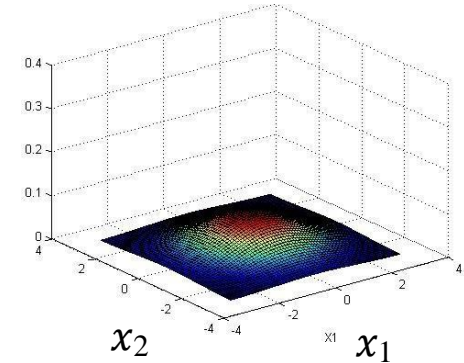
$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$



$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \Sigma = \begin{bmatrix} 0.6 & 0 \\ 0 & 0.6 \end{bmatrix}$$



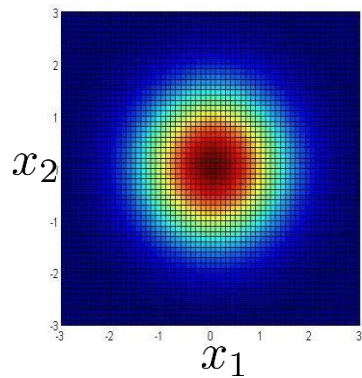
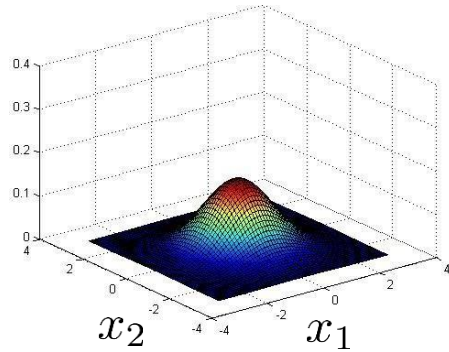
$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \Sigma = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}$$



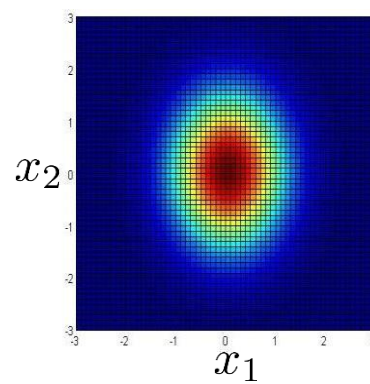
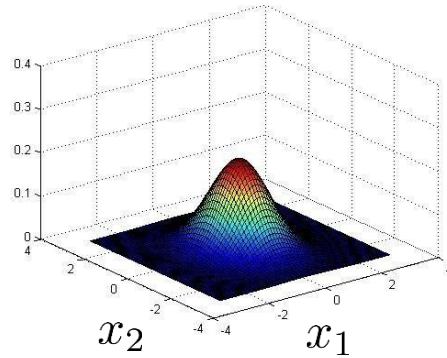
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28

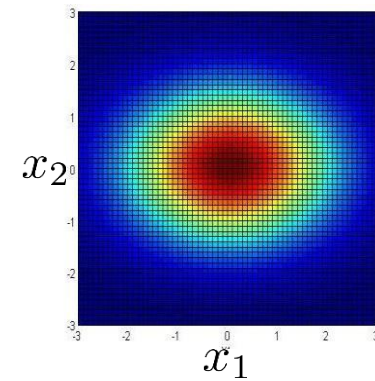
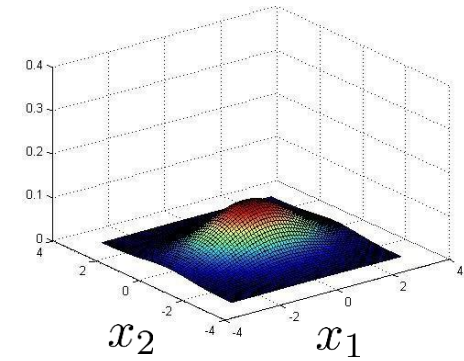
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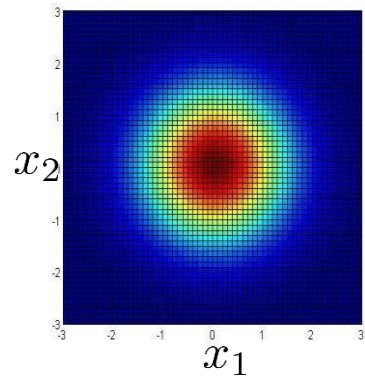
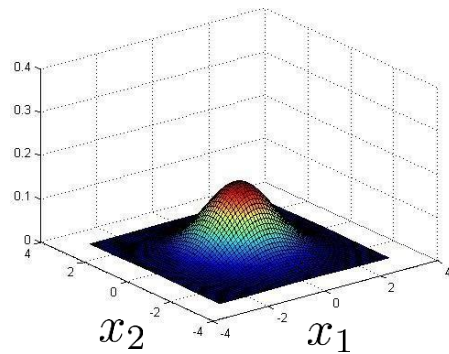
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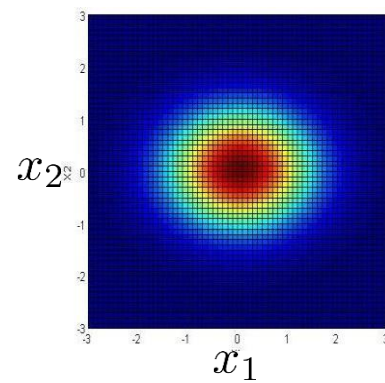
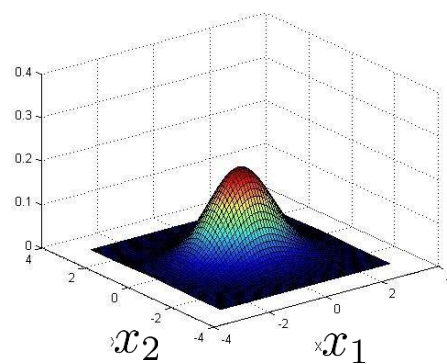
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29

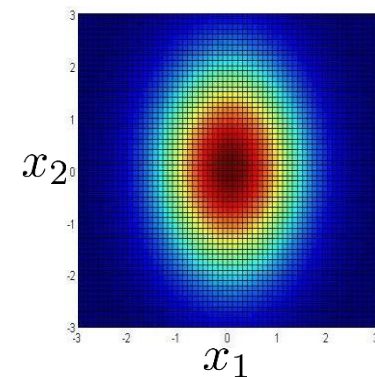
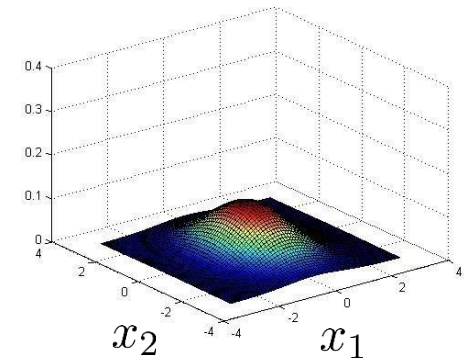
$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$



$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 0.6 \end{bmatrix}$$



$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$$

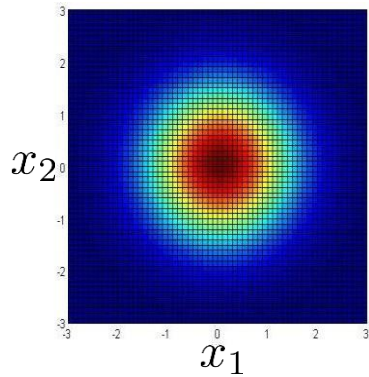
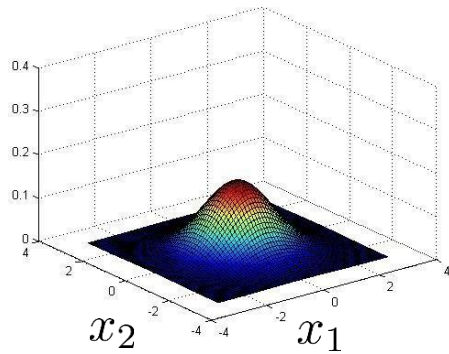




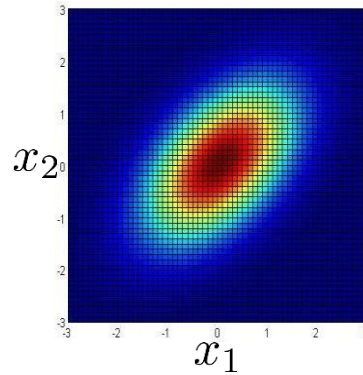
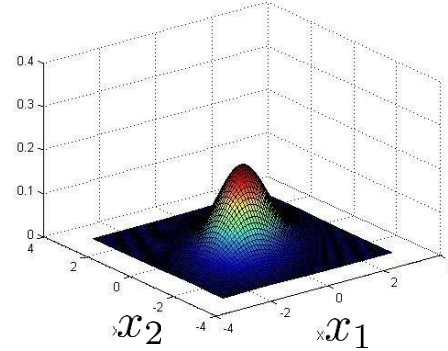
# Positive Correlation Between the Features

30

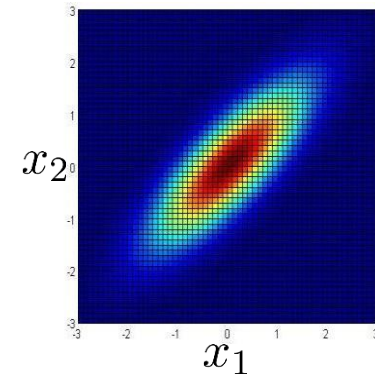
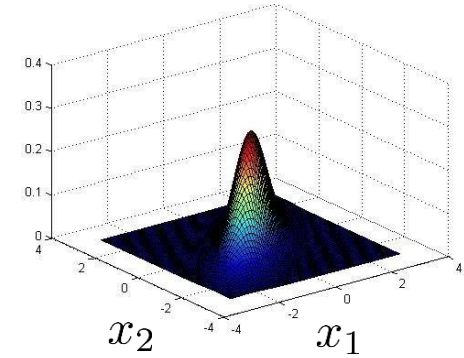
$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$



$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \Sigma = \begin{bmatrix} 1 & 0.5 \\ 0.5 & 1 \end{bmatrix}$$



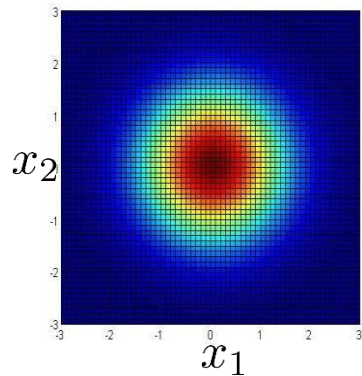
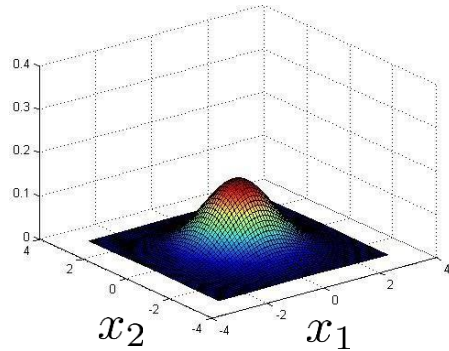
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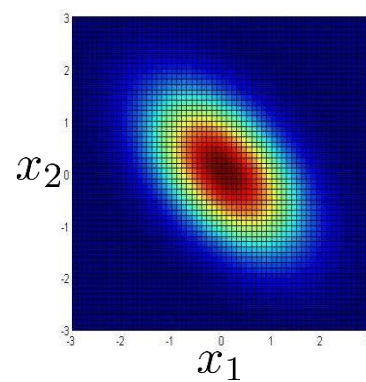
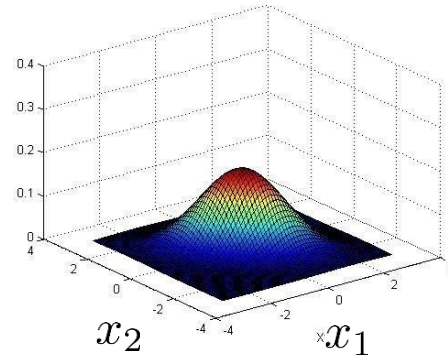
# Negative Correlation Between the Features

31

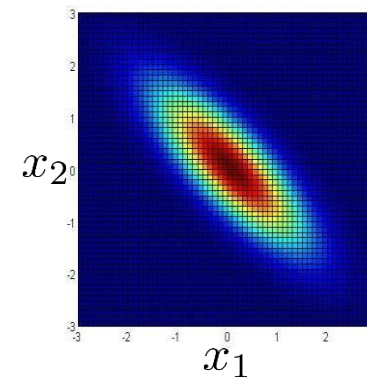
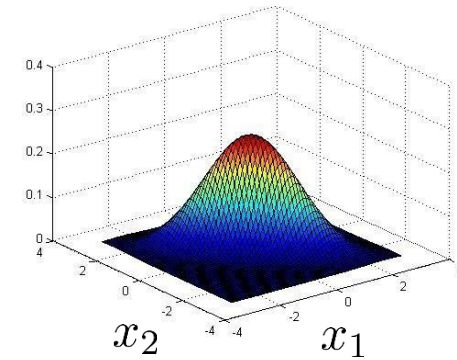
$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$



$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \Sigma = \begin{bmatrix} 1 & -0.5 \\ -0.5 & 1 \end{bmatrix}$$



$$\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \Sigma = \begin{bmatrix} 1 & -0.8 \\ -0.8 & 1 \end{bmatrix}$$

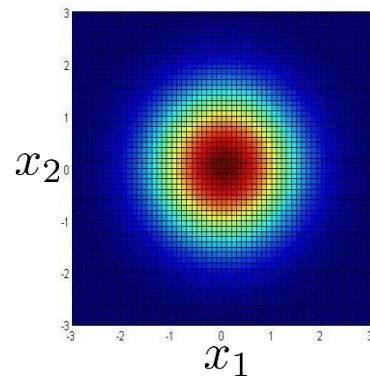
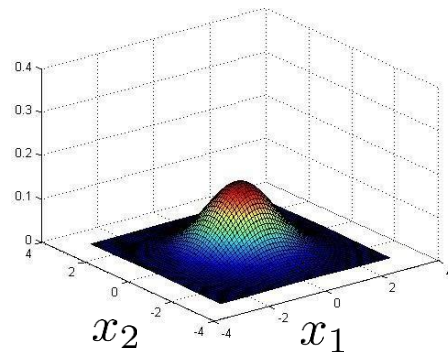




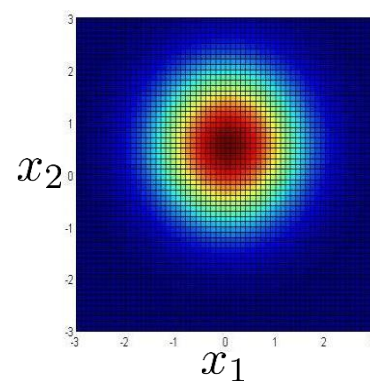
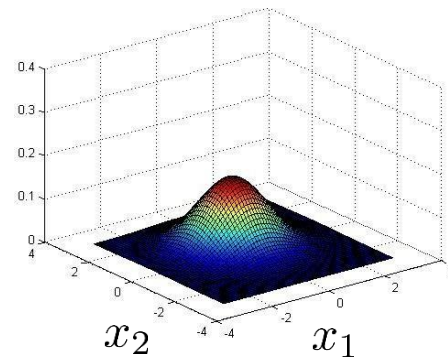
# Center (Mean) of Gaussian Distribution

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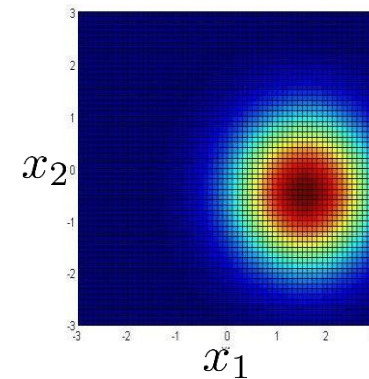
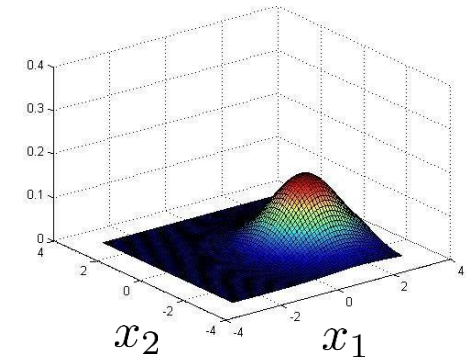
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$$\mu = \begin{bmatrix} 0 \\ 0.5 \end{bmatrix} \quad \Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$



$$\mu = \begin{bmatrix} 1.5 \\ -0.5 \end{bmatrix} \quad \Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$



# Anomaly Detection with Multivariate Gaussian Function

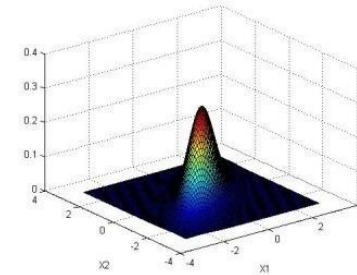
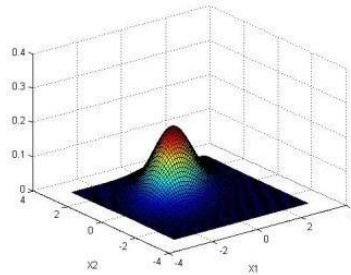
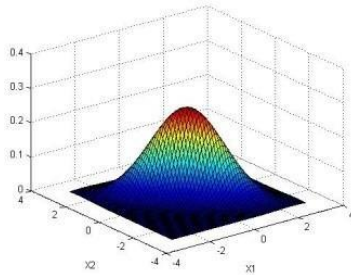


# Multivariate Gaussian Distribution

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□ Multivariate Gaussian distribution function.

$$p(x; \mu, \Sigma) = \frac{1}{|\Sigma|^{1/2} (2\pi)^{n/2}} \exp\left(-\frac{1}{2} (x - \mu)^T \Sigma^{-1} (x - \mu)\right)$$



□ Estimation of parameters.

$$\mu = \frac{1}{m} \sum_{i=1}^m x^{(i)}$$

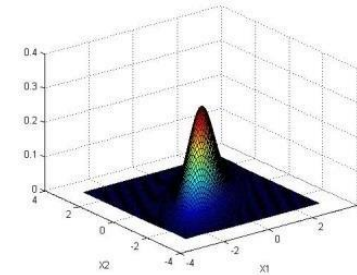
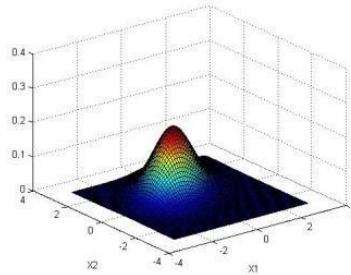
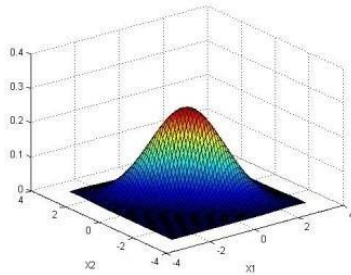
$$\Sigma = \frac{1}{m} \sum_{i=1}^m (x^{(i)} - \mu)(x^{(i)} - \mu)^T$$

# Multivariate Gaussian Distribution

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- Multivariate Gaussian distribution function.

$$p(x; \mu, \Sigma) = \frac{1}{|\Sigma|^{1/2} (2\pi)^{n/2}} \exp\left(-\frac{1}{2} (x - \mu)^T \Sigma^{-1} (x - \mu)\right)$$



- Estimation of parameters.

```
mu = np.mean(X, axis=0)
```

```
Sigma = np.cov(X.T)
```

# Algorithm

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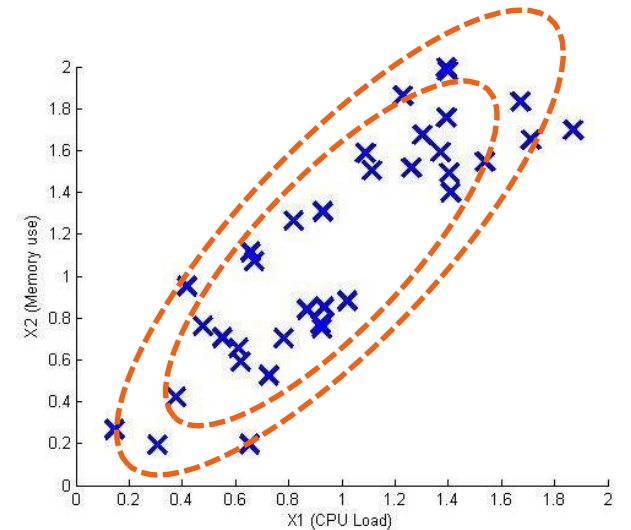
- Estimation of  $p(x)$  model parameters

$$\mu = \frac{1}{m} \sum_{i=1}^m x^{(i)} \quad \Sigma = \frac{1}{m} \sum_{i=1}^m (x^{(i)} - \mu)(x^{(i)} - \mu)^T$$

- Calculate the value of  $p(x)$  for the new data of  $x$

$$p(x; \mu, \Sigma) = \frac{1}{|\Sigma|^{1/2} (2\pi)^{n/2}} \exp\left(-\frac{1}{2} (x - \mu)^T \Sigma^{-1} (x - \mu)\right)$$

- Printing the **<<yes>>** output if  $p(x) < \epsilon$



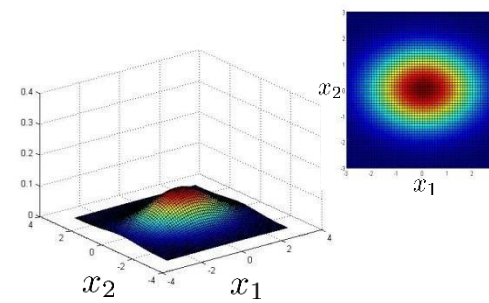
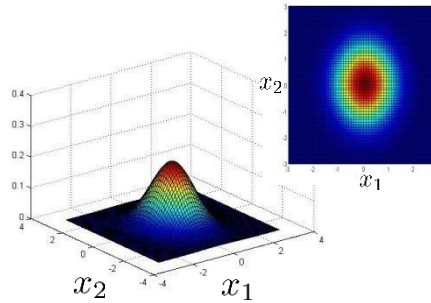
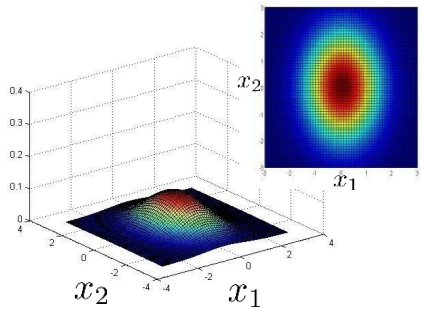
# Relation with the Primary Model

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## □ Primary model.

$$p(\mathbf{x}) = p(x_1; \mu_1, \sigma_1^2) p(x_2; \mu_2, \sigma_2^2) p(x_3; \mu_3, \sigma_3^2) \cdots p(x_n; \mu_n, \sigma_n^2)$$

$$\Sigma = \begin{bmatrix} \sigma_1^2 & 0 & \cdots & 0 \\ 0 & \sigma_2^2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \sigma_n^2 \end{bmatrix}$$



## □ Relation with multivariate Gaussian distribution.

$$p(\mathbf{x}; \mu, \Sigma) = \frac{1}{|\Sigma|^{1/2} (2\pi)^{n/2}} \exp\left(-\frac{1}{2} (\mathbf{x} - \mu)^T \Sigma^{-1} (\mathbf{x} - \mu)\right)$$

# Introductory Model or Multivariate Gaussian Distribution

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## □ Introductory model.

- Creating features is done manually. ( $x_1/x_2$ )
- Computational costs are relatively low.
- If the number of training samples is small, it still works correctly. [Number of parameters:  $2n$ ]

## □ Multivariate gaussian distribution.

- It automatically learns the correlation between features.
- Computational costs are high. [Calculating the inverse of the covariance matrix]
- The number of training samples should be more than the number of features. [Invertibility of matrix  $\Sigma$ ]